

# The power method

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Applications of matrix computations

## Introduction

The spectral properties of operators give valuable insight on various physical phenomena.

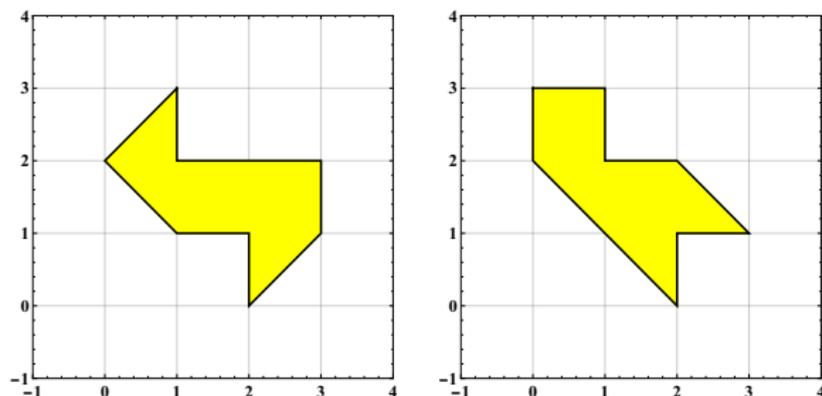


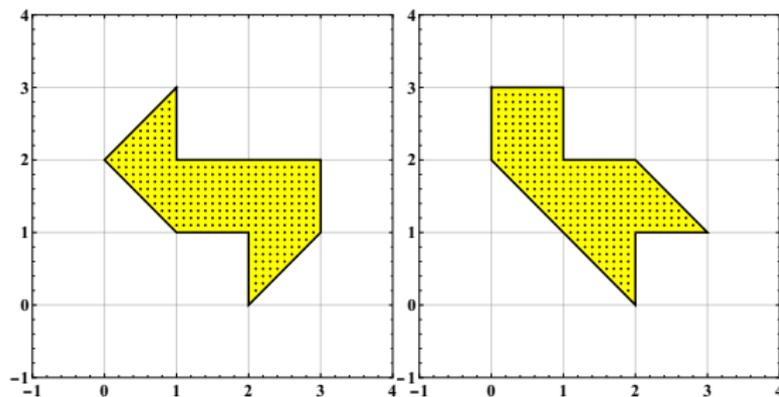
Figure: Isospectral drum shapes in 2D [Gordon, Webb, and Wolpert].

Two drums with clamped boundaries give the same sound if they have the same set of (Dirichlet) eigenvalues  $\lambda$  satisfying

$$-\Delta u = \lambda u \text{ in } D, \quad u|_{\partial D} = 0, \quad D \subset \mathbb{R}^2 \text{ bounded domain.}$$

## Discretization (FDM)

For a collection  $\{x_i\}_{i=1}^N$  of collocation points within the domain  $D$ , form the discretized solution vector  $\mathbf{u} = [u(x_1), \dots, u(x_N)]^T$ .



It is possible to discretize the Laplacian (incl. boundary conditions) as  $\Delta u \approx \mathbf{A}\mathbf{u}$ .

In consequence, the Dirichlet eigenvalue problem can be approximated by the matrix eigenvalue problem  $-\mathbf{A}\mathbf{u} = \lambda\mathbf{u}$ .

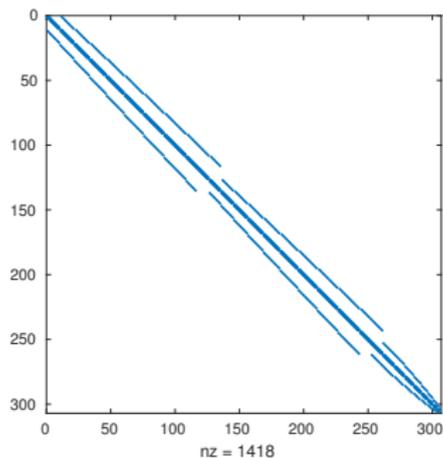
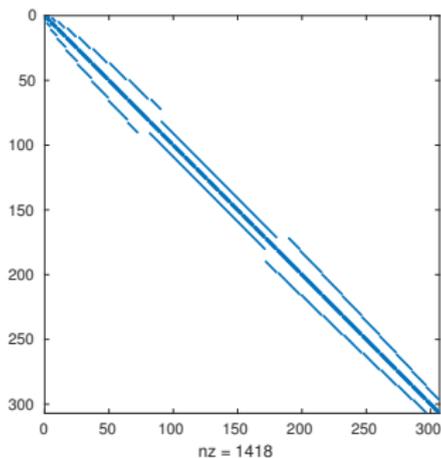


Figure: Left: the FDM matrix  $A$  of the first drum. Right: the FDM matrix  $B$  of the second drum. Both matrices have dimensions  $306 \times 306$ .

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>> norm(eig(A)-eig(B))
ans =
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8.8575e-12

## Eigenvalues of matrices

Let  $A$  be an  $n \times n$  matrix. Suppose that the pair  $(\lambda, \mathbf{v}) \in \mathbb{C} \times (\mathbb{C}^n \setminus \{\mathbf{0}\})$  satisfies

$$A\mathbf{v} = \lambda\mathbf{v}.$$

Then

- $\lambda$  is called an *eigenvalue* of matrix  $A$ .
- $\mathbf{v}$  is called an *eigenvector* of matrix  $A$ .

You should be familiar with the algebraic approach to solving the eigenvalues of  $A$ : by finding the roots of the characteristic polynomial  $p(\lambda) = \det(A - \lambda I)$ .

The eigenvector(s) corresponding to  $\lambda$  can be determined by solving the basis vectors spanning  $\text{Ker}(A - \lambda I)$  (usually by Gaussian elimination when computing by hand).

## Definition

The matrix  $A$  is called *diagonalizable* if it can be written as

$$A = PDP^{-1}$$

for some invertible  $n \times n$  matrix  $P$  and some diagonal matrix  $D = \text{diag}(\lambda_1, \dots, \lambda_n)$ .

By writing the columns of  $P$  as  $P = [\mathbf{v}_1, \dots, \mathbf{v}_n]$  the connection to eigenvalues becomes apparent:

$$A = PDP^{-1} \quad \Leftrightarrow \quad AP = PD$$

$$\Leftrightarrow A[\mathbf{v}_1, \dots, \mathbf{v}_n] = [\mathbf{v}_1, \dots, \mathbf{v}_n] \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix}$$

$$\Leftrightarrow [A\mathbf{v}_1, \dots, A\mathbf{v}_n] = [\lambda_1\mathbf{v}_1, \dots, \lambda_n\mathbf{v}_n]$$

$$\Leftrightarrow A\mathbf{v}_i = \lambda_i\mathbf{v}_i, \quad i \in \{1, \dots, n\}.$$

Some things to keep in mind:

- All real symmetric matrices  $A = A^T$  are diagonalizable (and, in fact, their eigenvalues and eigenvectors are real).
- The eigenvectors of a diagonalizable matrix form a basis for  $\mathbb{R}^n$ .
- The eigenvectors of a real symmetric matrix form an orthogonal basis for  $\mathbb{R}^n$ .
- Even if the matrix  $A$  is not diagonalizable, it still has a Jordan canonical form.

# Power method

Let  $A$  be a diagonalizable matrix such that  $A = PDP^{-1}$  for  $P = [\mathbf{v}_1, \dots, \mathbf{v}_n]$  and  $D = \text{diag}(\lambda_1, \dots, \lambda_n)$ . This of course means that

$$A\mathbf{v}_i = \lambda_i\mathbf{v}_i, \quad i \in \{1, \dots, n\},$$

and the eigenvectors  $\mathbf{v}_1, \dots, \mathbf{v}_n$  form a basis for  $\mathbb{R}^n$ . Let us assume that the eigenvalues are ordered  $|\lambda_1| > |\lambda_2| \geq \dots \geq |\lambda_n|$ , i.e., **the largest eigenvalue in modulus is a simple eigenvalue.**

Let us investigate the simple power iteration, where we begin by initializing a random vector  $\mathbf{x}^0 \in \mathbb{R}^n \setminus \{\mathbf{0}\}$  and proceed to compute the subsequent iterates as

$$\mathbf{x}^1 = A\mathbf{x}^0$$

$$\mathbf{x}^2 = A\mathbf{x}^1 = A^2\mathbf{x}^0$$

$$\mathbf{x}^3 = A\mathbf{x}^2 = A^3\mathbf{x}^0$$

$\vdots$

$$\mathbf{x}^k = A\mathbf{x}^{k-1} = A^k\mathbf{x}^0.$$

Let us write the arbitrary initial guess  $\mathbf{x}^0 \in \mathbb{R}^n$  using the eigenbasis of  $A$  as  $\mathbf{x}^0 = c_1 \mathbf{v}_1 + \cdots + c_n \mathbf{v}_n$ . In addition, we assume that  $c_1 \neq 0$ , that is, the initial guess contains a nonzero component in the direction of the dominant eigenvalue.<sup>1</sup>

Now  $A^k = PD^kP^{-1}$ , where  $D^k = \text{diag}(\lambda_1^k, \dots, \lambda_n^k)$ .

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<sup>1</sup>This is not a restricting assumption since in practice the initial guess is generated randomly. In particular, this means that the probability that  $c_1 = 0$  is zero.

Then

$$\begin{aligned} A^k \mathbf{x}^0 &= PD^k P^{-1}(c_1 \mathbf{v}_1 + \cdots + c_n \mathbf{v}_n) && (P^{-1} \mathbf{v}_i = \mathbf{e}_i) \\ &= PD^k(c_1 \mathbf{e}_1 + \cdots + c_n \mathbf{e}_n) = P(c_1 \lambda_1^k \mathbf{e}_1 + \cdots + c_n \lambda_n^k \mathbf{e}_n) && (P \mathbf{e}_i = \mathbf{v}_i) \\ &= \sum_{i=1}^n c_i \lambda_i^k \mathbf{v}_i = c_1 \lambda_1^k \mathbf{v}_1 + \sum_{i=2}^n c_i \lambda_i^k \mathbf{v}_i = \lambda_1^k \left( c_1 \mathbf{v}_1 + \sum_{i=2}^n c_i \left( \frac{\lambda_i}{\lambda_1} \right)^k \mathbf{v}_i \right). \end{aligned}$$

Hence

$$\frac{A^k \mathbf{x}^0}{\lambda_1^k} = c_1 \mathbf{v}_1 + \sum_{i=2}^n c_i \left( \frac{\lambda_i}{\lambda_1} \right)^k \mathbf{v}_i \xrightarrow{k \rightarrow \infty} c_1 \mathbf{v}_1$$

with convergence rate  $\mathcal{O}(|\lambda_2/\lambda_1|^k)$  as  $k \rightarrow \infty$ .<sup>2</sup>

Note that once the eigenvector  $\mathbf{v}_1$  is (approximately) known, the corresponding eigenvalue can be computed as

$$A \mathbf{v}_1 = \lambda_1 \mathbf{v}_1 \quad \Rightarrow \quad \lambda_1 = \frac{\mathbf{v}_1^T A \mathbf{v}_1}{\mathbf{v}_1^T \mathbf{v}_1}.$$

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<sup>2</sup>Landau's big-O notation:  $f(x) = \mathcal{O}(g(x))$  (as  $x \rightarrow \infty$ )  $\Leftrightarrow$  for some constant  $C > 0$ ,  $|f(x)| \leq C|g(x)|$  for sufficiently large  $x \gg 0$ . What is constant  $C$  here? :)

# Power method

## Algorithm

Start with an initial guess  $\mathbf{x}^0 \in \mathbb{R}^n \setminus \{\mathbf{0}\}$ .

**for**  $k = 1, 2, \dots$  **do**

    Compute  $\mathbf{y} = A\mathbf{x}^{k-1}$ ;

    Set  $\mathbf{x}^k = \mathbf{y}/\|\mathbf{y}\|$ ;

    Set  $\lambda_k = (\mathbf{x}^k)^T A\mathbf{x}^k$ ;

**end for**

The algorithm can be terminated once, e.g.,  $\|A\mathbf{x}^k - \lambda_k\mathbf{x}^k\| < \text{threshold}$ .

If the algorithm converges, then  $\mathbf{x} = \lim_{k \rightarrow \infty} \mathbf{x}_k$  and  $\lambda = \lim_{k \rightarrow \infty} \lambda_k$  satisfy  $A\mathbf{x} = \lambda\mathbf{x}$ , where  $\lambda$  is the largest eigenvalue of matrix  $A$  in modulus.

In applications involving discrete time Markov chains, the dominant eigenvector has a natural interpretation as a stationary probability distribution.

In part II, we will discuss Markov chains and their properties.

# Bibliography

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